

# Solving computational problems

(in environmental engineering)

# Computational methods

## Reasons for computer methods

*(iterative calculations)*

- Modeling
  - Forward modeling (numerical integration)
  - Inverse modeling (parameter estimation)
- Data analysis

## Classifications of models

- Mechanistic / Statistical
- Deterministic / Stochastic
- Analytical / Computational

## Reasons for modeling

- Prediction / Forecasting
- Understanding

Simulation → generate data

Data analysis → reduce amount of data

# Computational methods

Forward modeling

$$\mathbf{y} = F(\mathbf{x})$$

Inverse modeling

$$\hat{\mathbf{x}} = F^{-1}(\mathbf{y})$$

Data analysis



Numerical methods

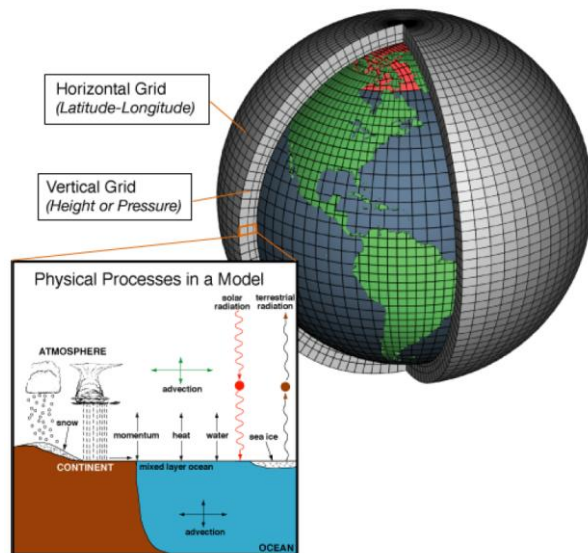
- Integration
- Differentiation
- Solving system of equations (root-finding in the univariate case)
- ...

# Models in environmental engineering

*“All models are wrong, but some are useful.”*

*- George P. Box*

# Mechanistic models continuum models



source: NOAA

TABLE I. Fundamental equations.

|  |  |      |
|--|--|------|
| Conservation of momentum:<br>(Newton's second law of motion) | $\frac{d\mathbf{V}}{dt} = -2\boldsymbol{\Omega} \times \mathbf{V} - \rho^{-1}\nabla p$ |      |
|  | $+ \mathbf{g} + \mathbf{F}$  | (T1) |
| Conservation of mass:<br>(continuity equation)               | $\frac{d\rho}{dt} = -\rho\nabla \cdot \mathbf{V} + C - D$                              | (T2) |
| Conservation of energy:<br>(first law of thermodynamics)     | $\frac{dI}{dt} = -p \frac{d\rho^{-1}}{dt} + Q$   | (T3) |
| Ideal gas law:<br>(approximate equation of state)            | $p = \rho RT$  | (T4) |

*Notation*

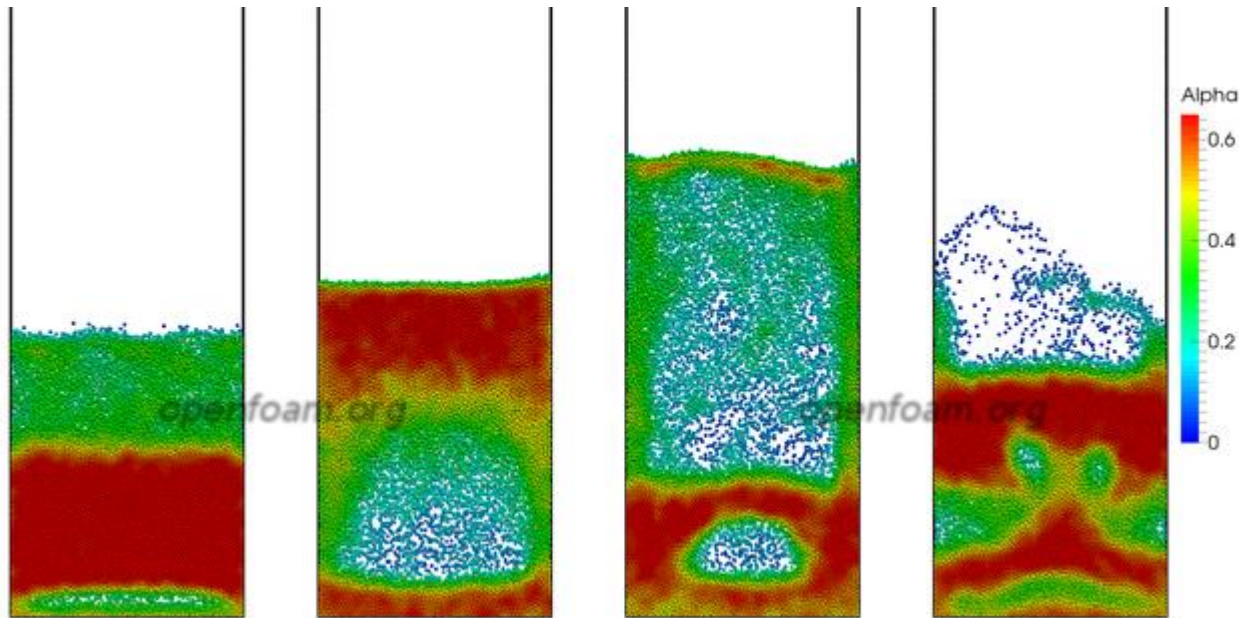
|                       |   |
|-----------------------|---|
| $\mathbf{V}$          | velocity relative to rotating earth   |
| $t$                   | time  |
| $\frac{d}{dt}$        | total time derivative $\left[ = \frac{\partial}{\partial t} + \mathbf{V} \cdot \nabla \right]$                    |
| $\boldsymbol{\Omega}$ | planet's angular rotation vector  |
| $\rho$                | atmospheric density   |
| $\mathbf{g}$          | apparent gravity $[ = \text{true gravity} - \boldsymbol{\Omega} \times (\boldsymbol{\Omega} \times \mathbf{r}) ]$ |
| $\mathbf{r}$          | position relative to planet's center  |
| $\mathbf{F}$          | force per unit mass   |
| $C$                   | rate of creation of (gaseous) atmosphere  |
| $D$                   | rate of destruction of atmosphere   |
| $I$                   | internal energy per unit mass $[ = c_v T ]$   |
| $Q$                   | heating rate per unit mass  |
| $R$                   | gas content   |
| $c_v$                 | specific heat at constant volume.   |

Numerically integrate over time/space

- Integration scheme
- Initial values
- Boundary values

# Mechanistic models

## discrete models



<https://openfoam.org/>

$$\mathbf{p} = m \mathbf{v}$$

$$\mathbf{F} = m \mathbf{a}$$

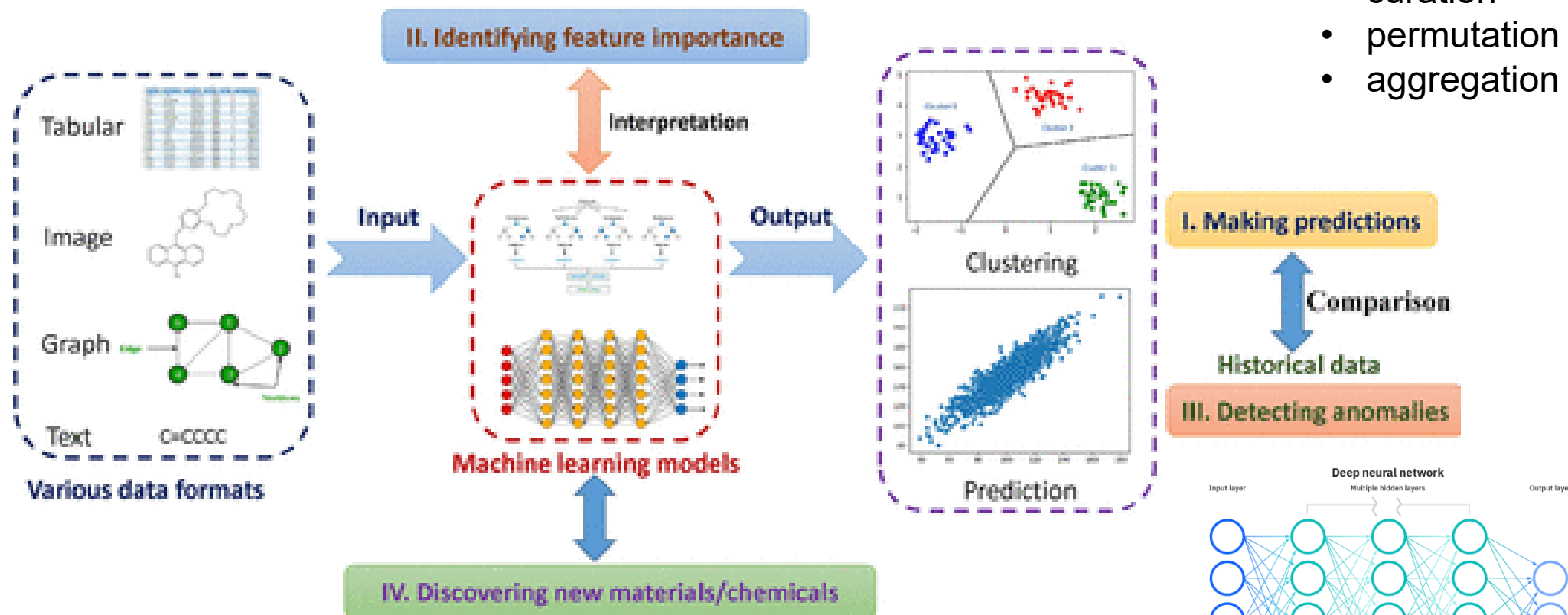
$$\mathbf{F}_{1 \rightarrow 2} = -\mathbf{F}_{2 \rightarrow 1}$$

source: Wikipedia

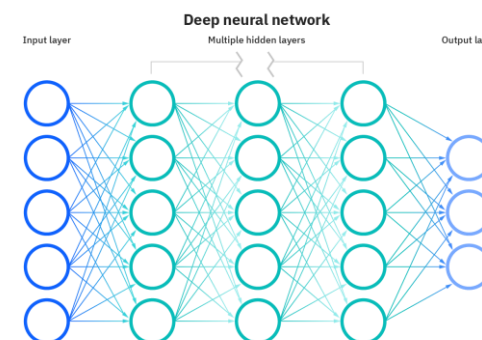
# Statistical models

Data preparation:

- cleaning
- curation
- permutation
- aggregation



Zhong et al., *ES&T*, 2021



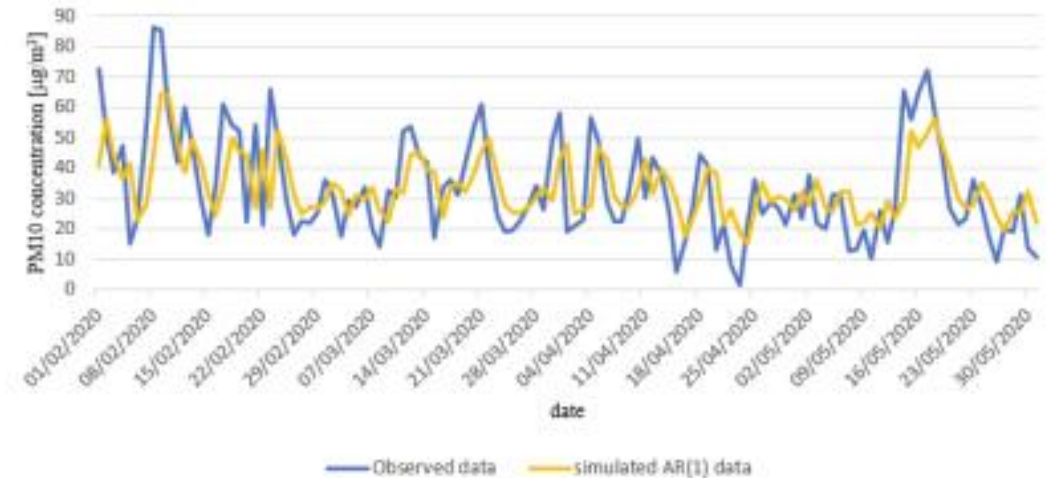
$$\sum_{i=1}^m w_i x_i + bias = w_1 x_1 + w_2 x_2 + w_3 x_3 + bias$$

$$output = f(x) = \begin{cases} 1 & \text{if } \sum w_i x_i + b \geq 0 \\ 0 & \text{if } \sum w_i x_i + b < 0 \end{cases}$$

# Statistical time series forecasting

Model present values based on previous values

$$X_t = \varphi_0 + \varphi_1 X_{t-1} + \dots + \varphi_p X_{t-p} + \varepsilon_t - \theta_1 \varepsilon_{t-1} - \dots - \theta_q \varepsilon_{t-q}$$





$$y(t) = LT(t) + S(t) + W(t) + E(t)$$

## Temporal and spatial analysis of ozone concentrations in Europe based on timescale decomposition and a multi-clustering approach

Eirini Boleti<sup>1,2</sup>, Christoph Hueglin<sup>1</sup>, Stuart K. Grange<sup>1,4</sup>, André S. H. Prévôt<sup>3</sup>, and Satoshi Takahama<sup>2</sup>

<sup>1</sup>Empa, Swiss Federal Laboratories for Materials Science and Technology, Überlandstrasse 129, 8600 Dübendorf, Switzerland

<sup>2</sup>EPFL, École Polytechnique Fédérale de Lausanne, Route Cantonale, 1015 Lausanne, Switzerland

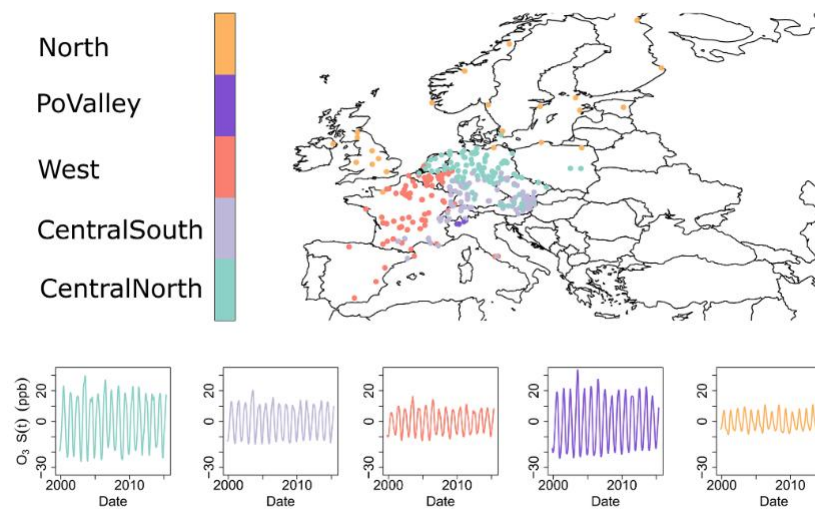
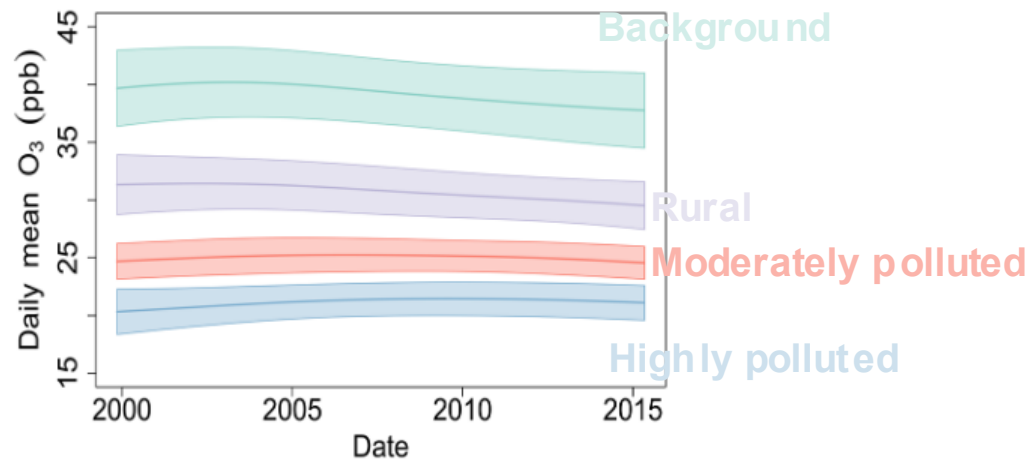
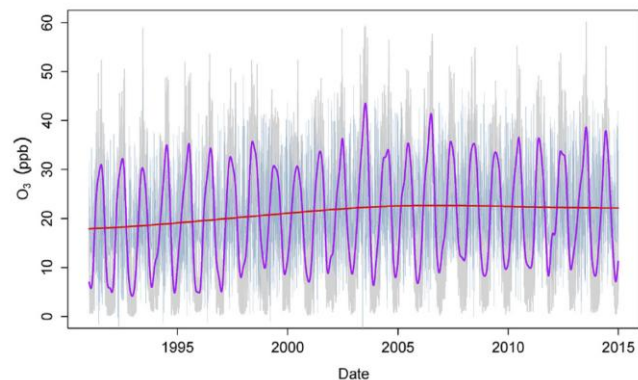
<sup>3</sup>PSI, Paul Scherrer Institute, 5232 Villigen, Switzerland

<sup>4</sup>Wolfson Atmospheric Chemistry Laboratories, University of York, York, YO10 5DD, UK

**Correspondence:** Christoph Hueglin (christoph.hueglin@empa.ch)

Received: 7 October 2019 – Discussion started: 30 October 2019

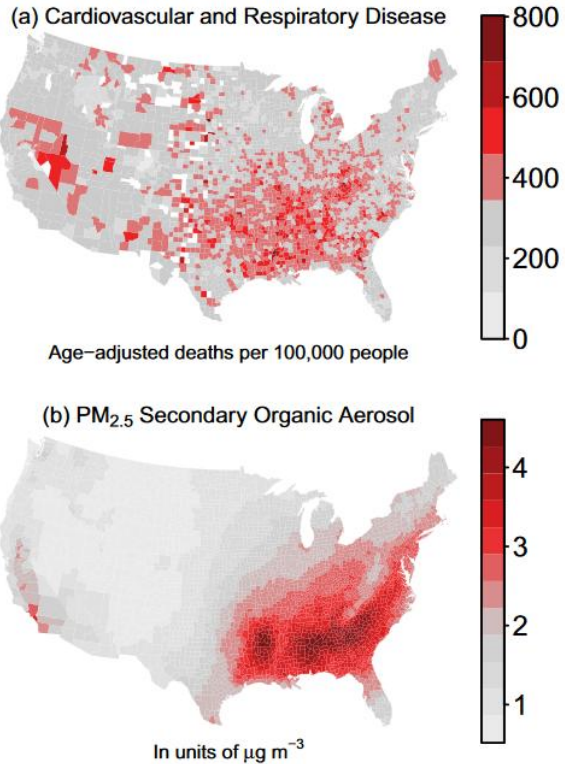
Revised: 16 March 2020 – Accepted: 30 March 2020 – Published: 30 July 2020



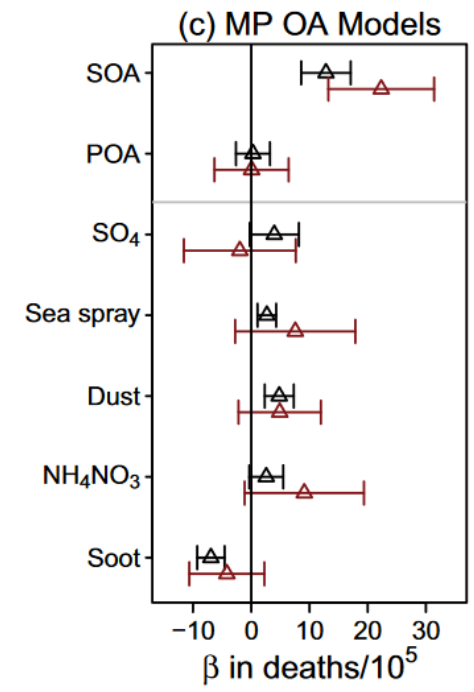


# Secondary organic aerosol association with cardiorespiratory disease mortality in the United States

Havala O. T. Pye<sup>1</sup>, Cavin K. Ward-Caviness<sup>2</sup>, Ben N. Murphy<sup>1</sup>, K. Wyat Appel<sup>1</sup> & Karl M. Seltzer<sup>3</sup>



$$D = \beta_0 + \{\beta_1 PM_{SOA_{BVOC}} + \beta_2 PM_{SOA_{AVOC}} + \beta_3 PM_{POA}\} + \beta_4 PM_{Seaspray} + \beta_5 PM_{Soot} + \beta_6 PM_{NH_4NO_3} + \beta_7 PM_{SO_4} + \beta_8 PM_{Dust} + \sum_{j=1}^N \beta'_j C_j$$



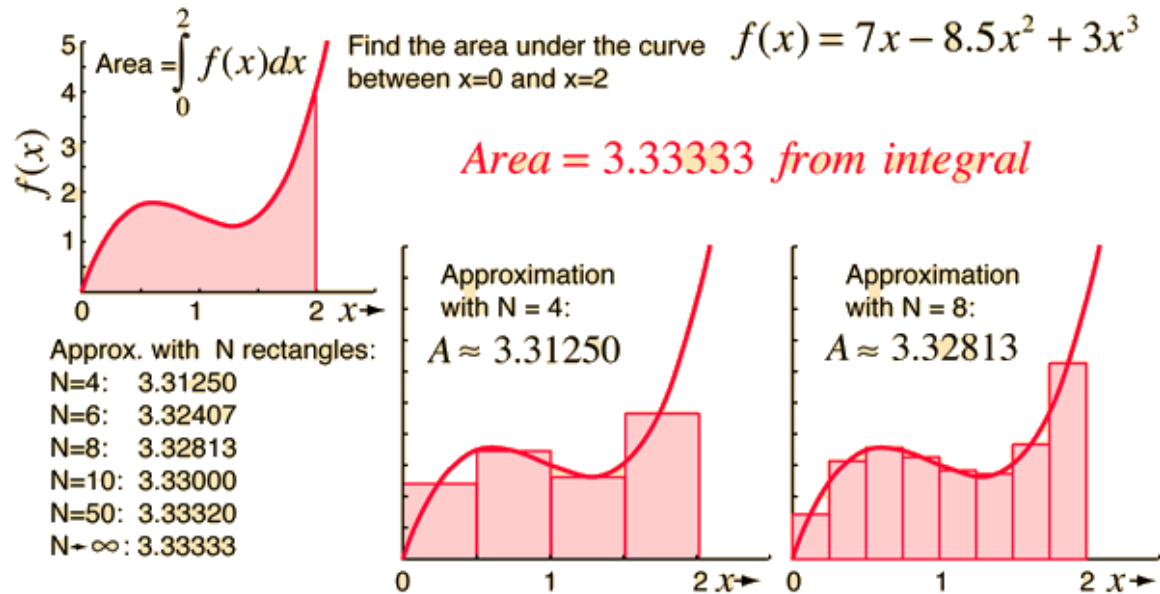
**Fig. 1** **Cardiorespiratory disease mortality rates and secondary organic aerosol concentrations.** County-level, year 2016 (a) cardiovascular and respiratory disease age-adjusted death rates (per 100,000 in population) are from CDC and (b) PM<sub>2.5</sub> secondary organic aerosol concentrations are predicted by CMAQ. White in (a) indicates no death rate data while light gray indicates low reported rates.

# Numerical methods

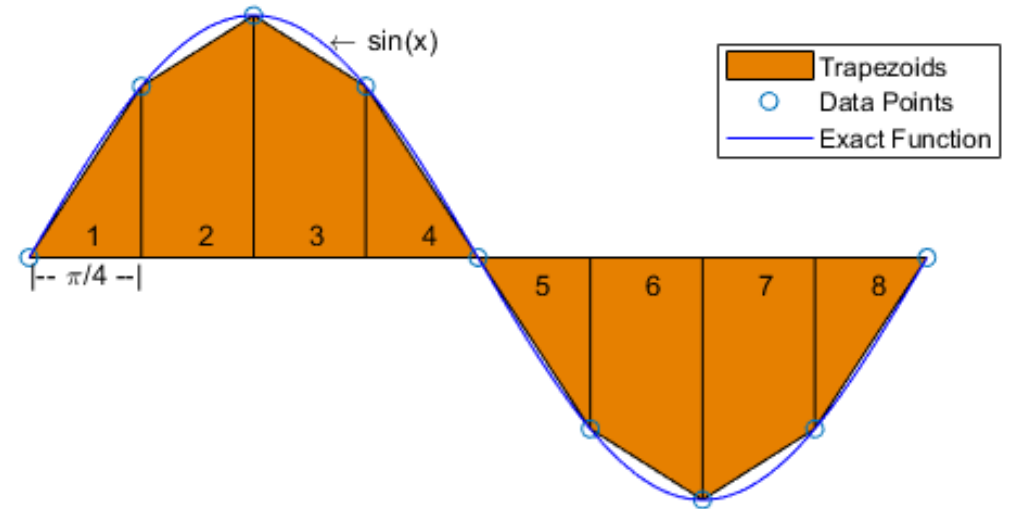
(Simplest examples selected)

# Numerical integration

## area under curve



<http://hyperphysics.phy-astr.gsu.edu/hbase/integ.html>

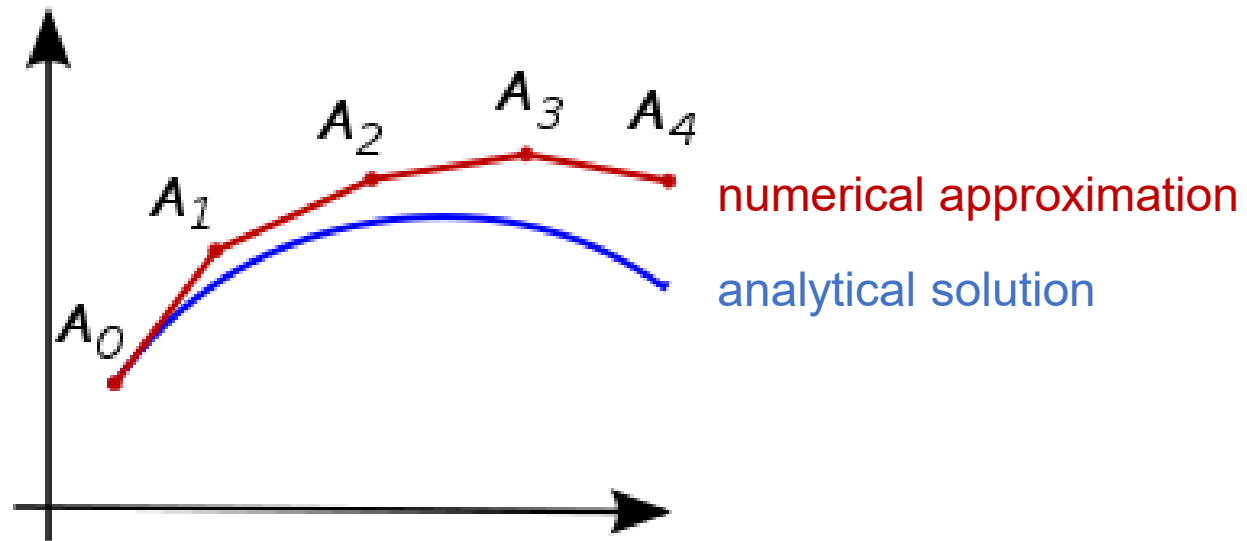


<https://ch.mathworks.com/help/matlab/ref/trapz.html>

# Numerical integration

## Initial value problem

$$y_{i+1} = y_i + \frac{dy}{dx} \Delta x$$

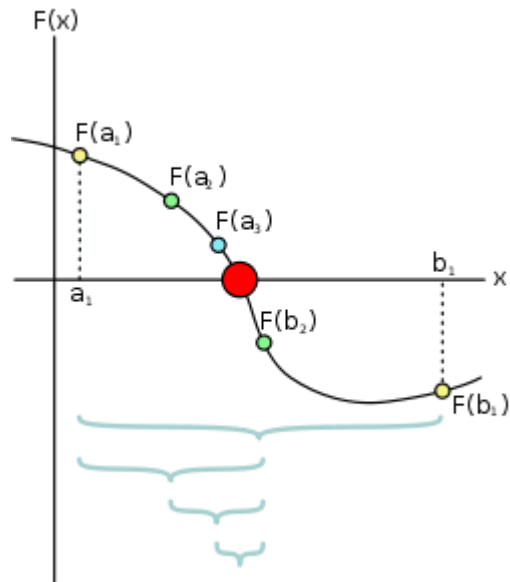


[https://en.wikipedia.org/wiki/Euler\\_method](https://en.wikipedia.org/wiki/Euler_method)

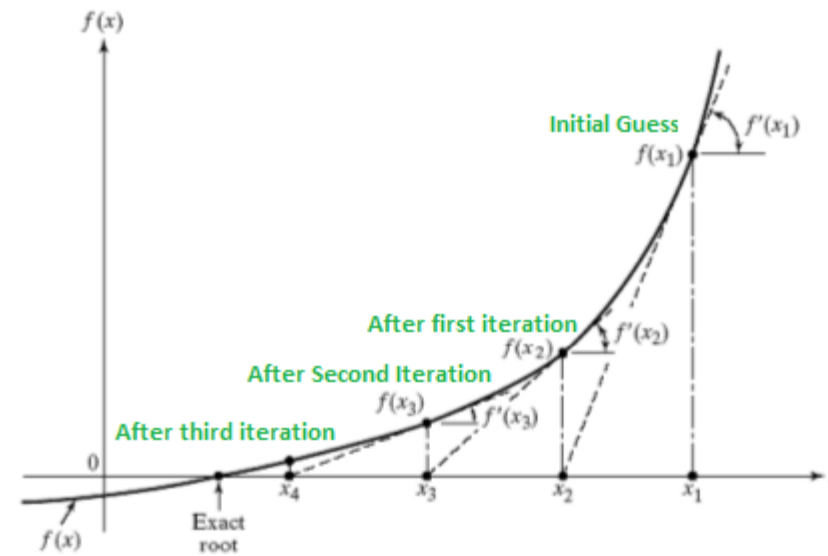
# Constraint satisfaction

## Root finding

Bisection method



Newton-Raphson method



[https://en.wikipedia.org/wiki/Bisection\\_method](https://en.wikipedia.org/wiki/Bisection_method)

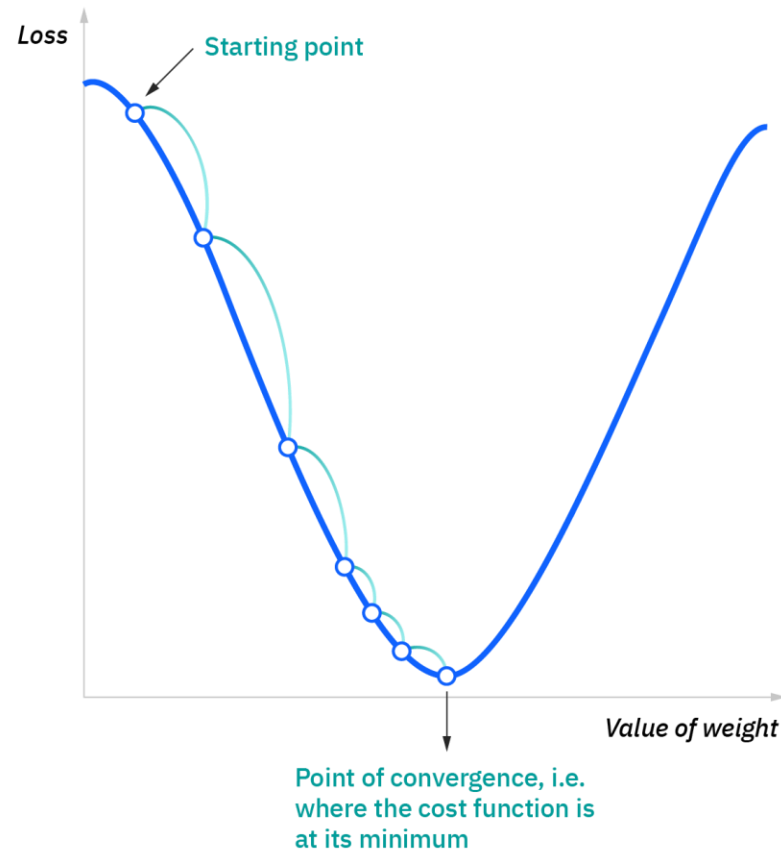
<https://www.geeksforgeeks.org/program-for-newton-raphson-method/>

# Parameter estimation

## Minimization

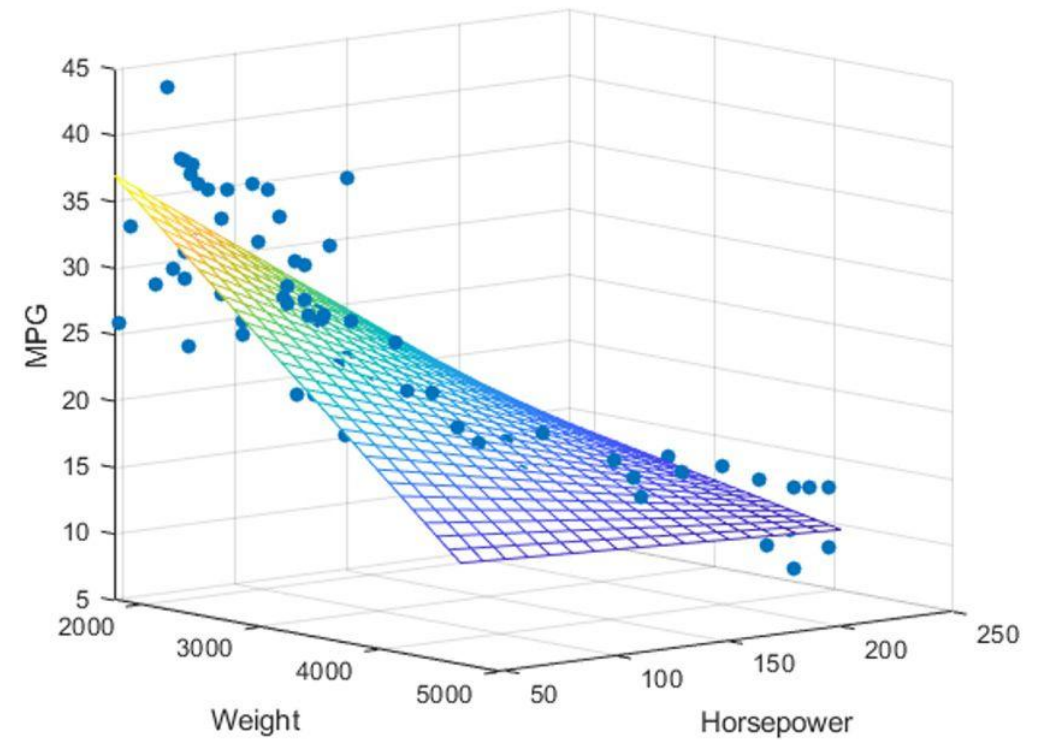
$$J = (\mathbf{y} - F(\mathbf{x}))^T (\mathbf{y} - F(\mathbf{x}))$$
$$\mathbf{x}_{i+1} = \mathbf{x}_i + \eta \nabla J(\mathbf{x}_i)$$

*(there are other ways to solve a least squares problem)*



# Regression

$$\begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} 1 & x_{11} & x_{12} & \cdots & x_{1q} \\ 1 & x_{21} & x_{22} & \cdots & x_{2q} \\ 1 & x_{31} & x_{32} & \cdots & x_{3q} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{n1} & x_{n2} & \cdots & x_{nq} \end{pmatrix} \begin{pmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_q \end{pmatrix} + \begin{pmatrix} \epsilon_1 \\ \epsilon_2 \\ \epsilon_3 \\ \vdots \\ \epsilon_n \end{pmatrix}$$



<https://ch.mathworks.com/discovery/linear-regression.html>

Coding

# “Wishful programming”

- To solve the problem, think about how you want to transform the data and what operations you need to perform to transform them
- Write out the operations without filling in the details (pseudo-code)
- Often programming can be done without the computer
- (90% of coding is spent debugging)

Example for Éolienne

```
for site = sites
time, speed = readfile(filename);
power = power_vectorized(speed);
electricitygen = integrate(time, power);
end
```

# Organizing code

- MANY ways to solve the same problem
- Some are preferred over others
  - Readability\*
    - parsimonious – no more variables and functions defined than necessary
    - short - also less place to introduce bugs
    - closer to mathematical formulae
    - declarative (describes *what* is being computed rather than *how* it's being computed)
  - Efficiency
    - vectorization
    - avoid defining same operation in multiple places
- \*There are two different ways in which code can be readable, and they can be orthogonal:
  - easy to read and understand what the whole program or sections of the program is doing at a glance
  - easy to read and understand what each step is doing

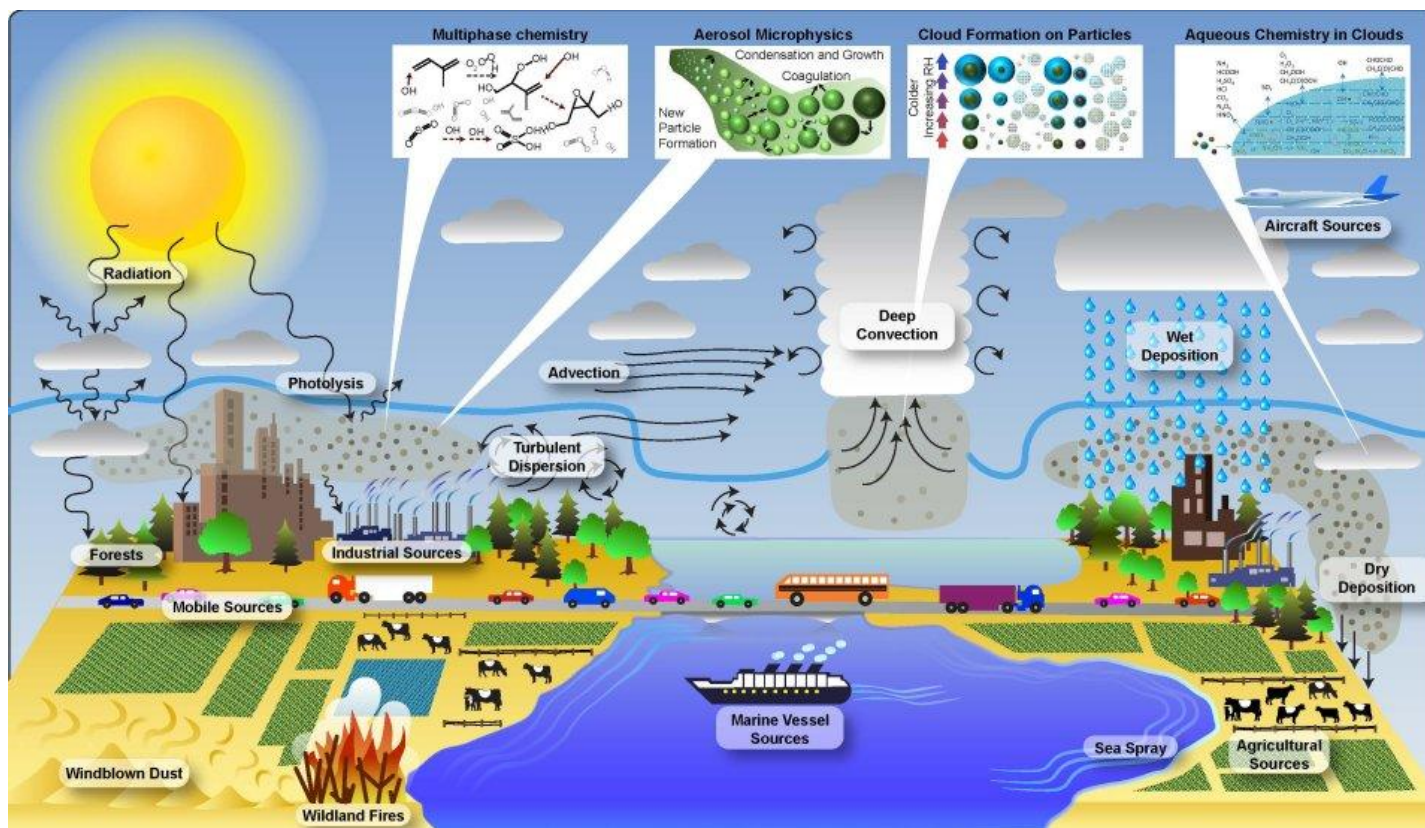
# Finding a solution to your project problem

## The value of simple models

(but don't make it too simple)

“Develop a computational model (e.g., simulation) of a real or hypothetical system to study its behavior.”

# Managing complexity



<https://www.epa.gov/sciencematters/cmaq-celebrating-25-years-air-quality-modeling-excellence>

## All models are wrong: reflections on becoming a systems scientist<sup>†</sup>

John D. Sterman\*  
Jay Wright Forrester Prize Lecture, 2002

- All models are wrong in that they are simplifications of reality – but they can be useful and we can learn from them.
- We should be aware of their limitations

YOU'RE TRYING TO PREDICT THE BEHAVIOR  
OF <COMPLICATED SYSTEM>? JUST MODEL  
IT AS A <SIMPLE OBJECT>, AND THEN ADD  
SOME SECONDARY TERMS TO ACCOUNT FOR  
<COMPLICATIONS I JUST THOUGHT OF>.

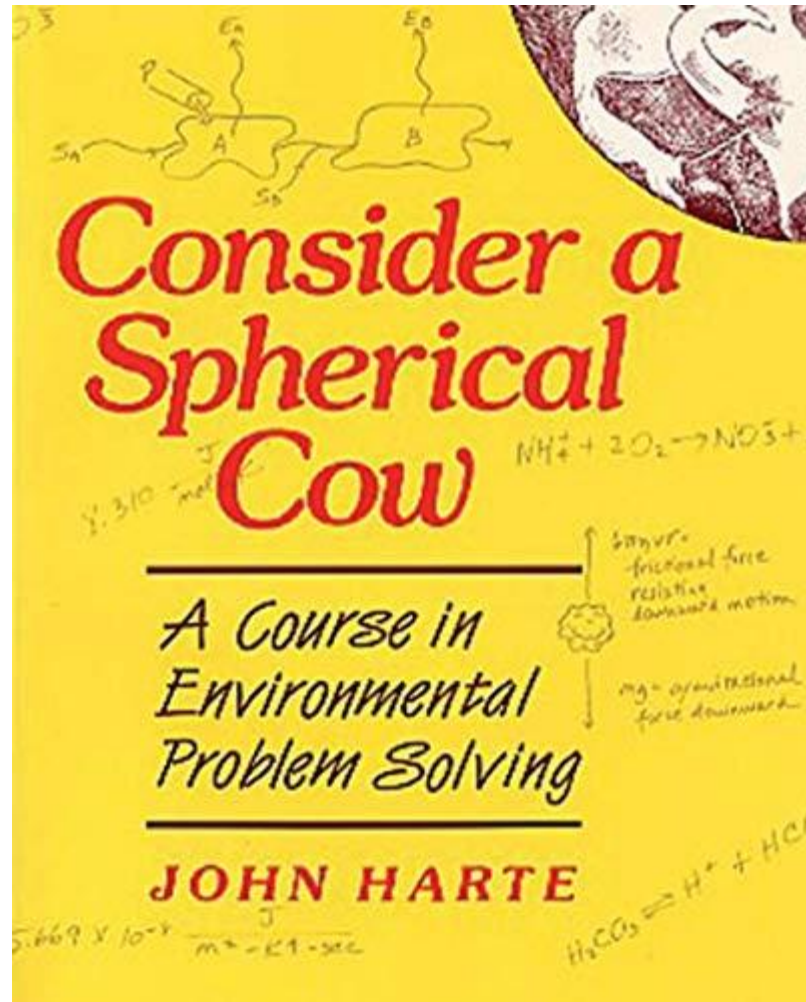
EASY, RIGHT?

SO, WHY DOES <YOUR FIELD> NEED  
A WHOLE JOURNAL, ANYWAY?



LIBERAL-ARTS MAJORS MAY BE ANNOYING SOMETIMES,  
BUT THERE'S *NOTHING* MORE OBNOXIOUS THAN  
A PHYSICIST FIRST ENCOUNTERING A NEW SUBJECT.

Source: [XKCD](#)



# Tips

Start with the question

Identify the simplest model / data set to answer this question

- You should be able to (roughly) justify your simplifications – sometimes it is a matter of time constraints of the project – speculate on its impact on your results, and improving it can be mentioned in your outlook
- Are you capturing the important physics / mechanisms / features of your system?

State whether the answer is within the expected order of magnitude

- Does it make sense?
- Can you compare it to any reference value?

*Note that you can change/redefine your project after the project proposal*